The Dynamics of Persuasion

Sid Redner, Santa Fe Institute (physics.bu.edu/~redner) CIRM, Luminy France, January 5-9, 2015

T. Antal, E. Ben-Naim, P. Chen, P. L. Krapivsky, M. Mobilia. V. Sood, F. Vazquez, D. Volovik + support from

Modeling Consensus:

- introduction to the voter model
- voter model on complex networks | lecture 1
- voting with some confidence
- majority rule

Modeling Discord & Diversity:

- 3-state voter models
- strategic voting
- bounded compromise
- dynamics of social balance
- Axelrod model

lecture 2

lecture 3

Persuasion Dynamics

Real People



People as interacting "atoms"

Voter Model

Clifford & Sudbury (1973) Holley & Liggett (1975)



0. Binary voter variable at each site i

I. Pick a random voter

2. Assume state of randomly-selected neighbor individual has no self-confidence & adopts neighbor's state

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3. Repeat 1 & 2 until consensus *necessarily* occurs in a finite system

Voter vs. Ising Models



Kinetic Ising model: *majority rule at T=0* Glauber (1963)



Voter Evolution vs. Ising Evolution



Voter Dornic et al. (2001)

Ising

droplet initial condition:

Lattice Voter Model: 3 Basic Properties

I. Final State (Exit) Probability $\mathcal{E}(\rho_0)$

Evolution of a single active link (homogeneous network):



I. Final State (Exit) Probability $\mathcal{E}(\rho_0)$

Evolution of a single active link (homogeneous network):



I. Final State (Exit) Probability $\mathcal{E}(\rho_0) = \rho_0$

Evolution of a single active link (homogeneous network):



2. Spatial Dependence of 2-Spin Correlations

flip rate:
$$w_i = \frac{1}{2} \left[1 - \frac{\sigma_i}{z} \sum_{j \in \langle i \rangle} \sigma_j \right]$$

I-spin correlations:

$$\frac{d\langle\sigma_i\rangle}{dt} = -2\langle\sigma_i w_i\rangle$$

2. Spatial Dependence of 2-Spin Correlations

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$$w_i = \frac{1}{2} \left[1 - \frac{\sigma_i}{z} \sum_{j \in \langle i \rangle} \sigma_j \right]$$

I-spin correlations:

$$\frac{d\langle \sigma_i \rangle}{dt} = -2\langle \sigma_i w_i \rangle \qquad \langle \sigma_i(t) \rangle = I_i(t) e^{-t}$$
$$= -\langle \sigma_i \rangle + \frac{1}{z} \sum_j \langle \sigma_j \rangle \qquad \text{for } \langle \sigma_i(t=0) \rangle = \delta_{i,0}$$

2-spin correlations:

$$\frac{d\langle\sigma_i\sigma_j\rangle}{dt} = -2\langle\sigma_i\sigma_j(w_i + w_j)\rangle$$
$$= -2\langle\sigma_i\sigma_j\rangle + \frac{1}{2d}\Big(\sum_{k\in\langle i\rangle}\langle\sigma_k\sigma_j\rangle + \sum_{k\in\langle j\rangle}\langle\sigma_i\sigma_k\rangle\Big)$$

2. Spatial Dependence of 2-Spin Correlations (infinite system) Equation for 2-spin correlation function:

$$\frac{d\langle\sigma_i\sigma_j\rangle}{dt} = -2\langle\sigma_i\sigma_j(w_i + w_j)\rangle$$

$$\frac{\partial c_2(\mathbf{r}, t)}{\partial t} = \nabla^2 c_2(\mathbf{r}, t)$$
$$c(r = 0, t) = 1; \quad c(r > 0, t = 0) = 0$$



2. Spatial Dependence of 2-Spin Correlations (infinite system) Equation for 2-spin correlation function: $\frac{d\langle \sigma_i \sigma_j \rangle}{dt} = -2\langle \sigma_i \sigma_j (w_i + w_j) \rangle \qquad \frac{\partial c_2(\mathbf{r}, t)}{\partial t} = \nabla^2 c_2(\mathbf{r}, t)$

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2. Spatial Dependence of 2-Spin Correlations (infinite system)

 $\frac{\partial c_2(\mathbf{r},t)}{\partial t} = \nabla^2 c_2(\mathbf{r},t)$

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Equation for 2-spin correlation function:

$$\frac{d\langle\sigma_i\sigma_j\rangle}{dt} = -2\langle\sigma_i\sigma_j(w_i + w_j)\rangle$$

Asymptotic solution:





3. System Size Dependence of Consensus Time

Liggett (1985), Krapivsky (1992)

 $\int^{\sqrt{Dt}} c(r,t)r^{d-1} \, dr = N$

dimension	consensus time
Ι	N ²
2	N In N
>2	N



3 Consensus	dimension	consensus time
Time		N²
1 111C	2	N In N
$\int \int c(\mathbf{r},t) d\mathbf{r} = N$	>2	N

Voter Model on Complex Networks

magnetization on regular networks



average magnetization conserved!

magnetization not conserved on complex networks



"flow" from high degree to low degree

Suchecki, Eguiluz & San Miguel (2005)

New Conservation Law



to compensate the different rates:

degree-weighted Ist moment:

$$\omega \equiv \frac{\sum_{k} k n_{k} \rho_{k}}{\sum_{k} k n_{k}} = \frac{\sum_{k} k n_{k} \rho_{k}}{\mu_{1}} \quad \text{conserved!}$$

 $\mu_1 = \text{av. degree}$ $n_k = \text{frac. nodes of degree } k$ $\rho_k = \text{frac.} \uparrow \text{ on nodes of degree } k$

Conservation Law for Voter Model

Transition probability

$$P[\eta \rightarrow \eta_{x}] = \sum_{\substack{y \ dxy \ dxy$$

Exit Probability on Complex Graphs $\mathcal{E}(\omega) = \omega$



Voter Model on Complex Networks

Sucheki, Eguiluz & San Miguel (2005) Sood & SR (2005) Antal, Sood & SR (2005)



warmup: complete graph

$$T(\rho) = \mathcal{R}(\rho)[T(\rho + d\rho) + dt] + \mathcal{L}(\rho)[T(\rho - d\rho) + dt] + [1 - \mathcal{R}(\rho) - \mathcal{L}(\rho)][T(\rho) + dt]$$

warmup: complete graph

$$T(\rho) = \mathcal{R}(\rho)[T(\rho + d\rho) + dt] \\ + \mathcal{L}(\rho)[T(\rho - d\rho) + dt] \\ + [1 - \mathcal{R}(\rho) - \mathcal{L}(\rho)][T(\rho) + dt]$$



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Consensus Time on Complete Graph

$$T(\rho) = \mathcal{R}(\rho)[T(\rho + d\rho) + dt] + \mathcal{L}(\rho)[T(\rho - d\rho) + dt] + [1 - \mathcal{R}(\rho) - \mathcal{L}(\rho)][T(\rho) + dt]$$

continuum limit:
$$T'' = -\frac{N}{\rho(1-\rho)}$$

solution:

$$T(\rho) = -N \left[\rho \ln \rho + (1 - \rho) \ln(1 - \rho) \right]$$

Consensus Time on Heterogeneous Networks

 $T(\{\rho_k\}) \equiv$ av. consensus time starting with density ρ_k on nodes of degree k

$$T(\{\rho_k\}) = \sum_k \mathcal{R}_k(\{\rho_k\})[T(\{\rho_k^+\}) + dt]$$

+
$$\sum_k \mathcal{L}_k(\{\rho_k\})[T(\{\rho_k^-\}) + dt]$$

+
$$\left[1 - \sum_k [\mathcal{R}_k(\{\rho_k\}) + \mathcal{L}_k(\{\rho_k\})]\right][T(\{\rho_k\}) + dt]$$

$$\mathcal{R}_k(\{\rho_k\}) = \operatorname{prob}(\rho_k \to \rho_k^+) \qquad \mathcal{L}_k(\{\rho_k\}) = n_k\rho_k(1 - \omega)$$

=
$$\frac{1}{N} \sum_x' \frac{1}{k_x} \sum_y P(\downarrow, --, \uparrow)$$

=
$$n_k \omega(1 - \rho_k)$$

Consensus Time on Heterogeneous Networks

continuum limit:

$$\sum_{k} \left[(\omega - \rho_k) \frac{\partial T}{\partial \rho_k} + \frac{\omega + \rho_k - 2\omega \rho_k}{2Nn_k} \frac{\partial^2 T}{\partial \rho_k^2} \right] = -1$$

Voter Model on Complex Networks configuration model



Consensus Time on Heterogeneous Networks

continuum limit:

$$\sum_{k} \left[(\omega - \rho_{k}) \frac{\partial T}{\partial \rho_{k}} + \frac{\omega + \rho_{k} - 2\omega\rho_{k}}{2Nn_{k}} \frac{\partial^{2}T}{\partial \rho_{k}^{2}} \right] = -1$$
now use $\rho_{k} \to \omega \quad \forall k$
and $\frac{\partial}{\partial \rho_{k}} = \frac{\partial \omega}{\partial \rho_{k}} \frac{\partial}{\partial \omega} = \frac{kn_{k}}{\mu_{1}} \frac{\partial}{\partial \omega}$
to give $\frac{\partial^{2}T}{\partial \omega^{2}} = -\frac{N\mu_{1}^{2}/\mu_{2}}{\omega(1 - \omega)} \quad \underset{as}{\text{same}} \quad T'' = -\frac{N}{\rho(1 - \rho)}$
with effective size $N_{\text{eff}} = N \, \mu_{1}^{2}/\mu_{2}$
 $\mu_{n} = \sum_{k} k^{n} n_{k}$

Consensus Time for Complex Networks with $n_k \sim k^{-\nu}$

$$T_N \propto N_{\rm eff} = N \frac{\mu_1^2}{\mu_2}$$

Consensus Time for Complex Networks with $n_k \sim k^{-\nu}$ $\nu > 3$ $T_N \propto N_{\text{eff}} = N \frac{\mu_1^2}{\mu_2} \sim \langle$
Consensus Time for Complex Networks with $n_k \sim k^{-\nu}$ $T_N \propto N_{\text{eff}} = N \frac{\mu_1^2}{\mu_2} \sim \begin{cases} N & \nu > 3\\ N/\ln N & \nu = 3 \end{cases}$

Consensus Time for Complex Networks with $n_k \sim k^{-\nu}$ $T_N \propto N_{\text{eff}} = N \frac{\mu_1^2}{\mu_2} \sim \begin{cases} N & \nu > 3\\ N/\ln N & \nu = 3\\ N^{2(\nu-2)/(\nu-1)} & 2 < \nu < 3\\ (\ln N)^2 & \nu = 2\\ \mathcal{O}(1) & \nu < 2 \end{cases}$ fast consensus Invasion process: $T_N \sim \begin{cases} N & \nu > 2, \\ N \ln N & \nu = 2, \\ N^{2-\nu} & \nu < 2. \end{cases}$

motivation: Centola (2010) related work: Dall'Asta & Castellano (2007)



motivation: Centola (2010) related work: Dall'Asta & Castellano (2007)





motivation: Centola (2010) related work: Dall'Asta & Castellano (2007)





extremal

motivation: Centola (2010) related work: Dall'Asta & Castellano (2007)





marginal

Simplest case: 2 internal states densities P_0 , P_1 , M_0 , M_1 , with $P_0+P_1+M_0+M_1=I$

basic processes:

 $M_1 P_1 \longrightarrow P_0 P_1 \text{ or } M_0 M_1$ $P_0 P_1 \longrightarrow P_0 P_1 \text{ or } P_0 P_0$ $M_1 P_0 \longrightarrow M_1 P_1 \text{ or } P_0 P_0$

 M_1 P_1 unsure M_0 P_0 confident

 $M_0 P_0 \longrightarrow M_0 P_1 \text{ or } M_1 P_0$ $M_0 M_1 \longrightarrow M_0 M_1 \text{ or } M_0 M_0$ $M_0 P_1 \longrightarrow M_1 P_1 \text{ or } M_0 M_0$

rate equations/mean-field limit: $\dot{P}_0 = -M_0P_0 + M_1P_1 + P_0P_1$ $\dot{P}_1 = M_0P_0 - M_1P_1 - P_0P_1 + (M_1P_0 - M_0P_1)$ similarly for M₀, M₁ special soluble case: symmetric limit

$$P_0 + P_1 = M_0 + M_1 = \frac{1}{2}$$

 $\dot{P}_0 = -M_0 P_0 + M_1 P_1 + P_0 P_1$ $\dot{P}_1 = M_0 P_0 - M_1 P_1 - P_0 P_1 + (M_1 P_0 - M_0 P_1)$

$$\dot{P}_0 = -\dot{P}_1 = P_0^2 + \frac{1}{2}P_0 - \frac{1}{4}$$

$$= -(P_0 - \lambda_+)(P_0 - \lambda_-)$$

$$\lambda_{\pm} = \frac{1}{4}(-1\pm\sqrt{5}) \approx 0.309, -0.809$$

solution:
$$\frac{P_0(t) - \lambda_+}{P_0(t) - \lambda_-} = \frac{P_0(0) - \lambda_+}{P_0(0) - \lambda_-} e^{-(\lambda_+ - \lambda_-)t}$$

near symmetric $P_0 = \frac{1}{2} + 10^{-5}, M_0 = \frac{1}{2} - 10^{-5}, P_1 = M_1 = 0$ limit:





Consensus Time in Two Dimensions



Consensus Time Distribution





two time scales control approach to consensus see also Spirin, Krapivsky, SR (2001), Chen & SR (2005) Ising model Majority vote model

Majority rule

Galam (1999), Krapivsky & SR (2003), Slanina & Lavicka (2003), Chen & SR (2005)

- I. Pick a random group of G spins (with G odd).
- 2. All spins in G adopt the majority state.
- 3. Repeat until consensus necessarily occurs.



Basic questions: *1.* Which final state is reached?

2. What is the time until consensus?

Mean-field theory (for G=3)

 $E_n \equiv \text{exit probability to } m = 1 \text{ starting from } n \text{ plus spins}$

 $= p_n E_{n+1} + q_n E_{n-1} + r_n E_n$



 $T_n \equiv \text{mean time to } m = 1 \text{ starting from } n \text{ plus spins}$ = $p_n(T_{n+1} + \delta t) + q_n(T_{n-1} + \delta t) + r_n(T_n + \delta t)$ Exit probability (schematic)

Consensus time (data)



Consensus time for finite spatial dimensions



Critical dimension appears to be >4!

Anomalous dynamics in 2d: stripes ~33% of the time!



t=20

t=80

Slab formation in 3d ~8% of the time



Consensus time distribution



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- Áxelrod model





lecture 3

Discord & Diversity

If people are reasonable, why is consensus hard to reach? Possibilities: • insufficient communication

- appreciable diversity
- stubbornness
- your favorite mechanism

Models:

Three voting states:- 0 +; -+ noninteractingVazquez & SR (2004)Strategic voting:ideology vs. strategyVolovik, Mobilia & SR (2009)Bounded confidence:compromise only when close
Deffuant, Neau, Amblard & Weisbuch (2000)
Hegselmann & Krause (2002)
Ben Naim, Krapivsky & SR (2003)Social balance:dynamics of positive/negative links
Antal, Krapivsky & SR (2005, 2006)Axelrod model:many features, many traits
Axelrod (1997)

Axelrod (1997) Castellano, Marsili & Vespignani (2000) Vazquez & SR (2007)

Three Voting States: - 0 +

- 0.3-state voter at each site: -0 +
- I. Pick a random voter
- 2. Assume state of neighbor if compatible
- 3. Repeat until either consensus or frozen final state





Evolution in Composition Triangle



Evolution in Composition Triangle



The Phase Diagram

 $F(\rho_{-}, \rho_{+}) =$ prob. to reach frozen state starting from (ρ_{-}, ρ_{+})

recursion: $F(\rho_{-}, \rho_{+}) = p_{x} \left[F(\rho_{-} - \delta, \rho_{+}) + F(\rho_{-} + \delta, \rho_{+}) \right]$ = $p_{y} \left[F(\rho_{-}, \rho_{+} - \delta) + F(\rho_{-}, \rho_{+} + \delta) \right]$ = $\left[1 - 2(p_{x} + p_{y}) \right] F(\rho_{-}, \rho_{+})$



The Phase Diagram

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Phase Diagram & Final State Probabilities



moral: extremism promotes deadlock

Strategic Voting¿vote for first choice?¿vote against last choice?

UK elections 1830-2010



evolution of the densities a, b, c:

$$\dot{a} =$$

 $\dot{b} =$
 $\dot{c} =$

evolution of the densities a, b, c:

$$\dot{a} = T(b + c - 2a)$$
$$\dot{b} = T(c + a - 2b)$$
$$\dot{c} = T(a + b - 2c)$$

evolution of the densities a, b, c:

$$\dot{a} = T(b + c - 2a) + r_{AC} ac + r_{AB} ab$$

$$\dot{b} = T(c + a - 2b) + r_{BA} ba + r_{BC} bc$$

$$\dot{c} = T(a + b - 2c) + r_{CA} ca + r_{CB} cb$$

evolution of the densities a, b, c:

$$\dot{a} = T(b + c - 2a) + r_{AC} ac + r_{AB} ab$$

$$\dot{b} = T(c + a - 2b) + r_{BA} ba + r_{BC} bc$$

$$\dot{c} = T(a + b - 2c) + r_{CA} ca + r_{CB} cb$$
strategic voting
$$r_{AB} = -r_{BA} = \begin{cases} +r & B \text{ minority} \\ 0 & C \text{ minority} \\ -r & A \text{ minority} \end{cases}$$

two natural r = const. too drastic choices $r = r_0[(a+b)/2 - c]$ better $\dot{a} = T(1 - 3a) + rac$

$$\rightarrow \dot{b} = T(1 - 3b) + rbc \quad \text{in } c_{<} \text{ sector}$$
$$\dot{c} = T(1 - 3c) - rc(1 - c)$$



$$egin{aligned} \dot{c} &= (1-3c)T - rac{r_0}{2}c(1-c)(1-3c) & c_3 = rac{1}{3} \ c_\pm &= rac{1}{2}\left(1\pm\sqrt{1-8x_0}
ight) \ &\equiv -rac{3r_0}{2}(c-c_-)(c-c_+)(c-c_3) & x_0 \equiv rac{T}{r_0} \end{aligned}$$

$$\begin{bmatrix} \frac{c(t) - c_3}{c(0) - c_3} \end{bmatrix}^{\alpha_3} \begin{bmatrix} \frac{c(t) - c_+}{c(0) - c_+} \end{bmatrix}^{\alpha_+} \begin{bmatrix} \frac{c(t) - c_-}{c(0) - c_-} \end{bmatrix}^{\alpha_-} = e^{-3(c_+ - c_-)r_0t/2}$$
$$\alpha_{\pm} = \frac{1}{c_3 - c_{\pm}} \qquad \alpha_3 = \alpha_- - \alpha_+ = \frac{c_+ - c_-}{(c_3 - c_+)(c_3 - c_-)}$$



location of fixed point


Simulations of Strategic Voter Model



Bounded Compromise Model



If $|x_2 - x_1| < 1$ compromise

If $|x_2 - x_1| > 1$ no interaction

The Opinion Distribution

P(x,t) = probability that agent has opinion x at time t

Fundamental parameter: Δ the diversity (initial opinion range)

 Δ <1: consensus Δ >1: fragmentation

$$w \sim e^{-\Delta t/2}$$

$$\frac{\partial P(x,t)}{\partial t} = \iint dx_1 dx_2 P(x_1,t) P(x_2,t) \times \left[\delta\left(x - \frac{1}{2}(x_1 + x_2)\right) - \delta(x - x_1)\right]$$

$$gain by$$

$$averaging$$

$$dveraging$$

$$dver$$

same as Maxwell model for inelastic collisions & inelastic collapse phenomena

Ben-Naim and Krapivsky (2000) Baldassarri, Marconi, Puglisi (2001) Ben-Naim, Krapvisky, SR (2003)

Early time evolution (for $\Delta = 4.2$)

integrate master equation rather than simulate!



Early time evolution (for $\Delta = 4.2$)

integrate master equation rather than simulate!



Early time evolution (for $\Delta = 4.2$) integrate master equation rather than simulate!



Early time evolution (for $\Delta = 4.2$)

integrate master equation rather than simulate!









Birth of Extremists



A Possible Realization 1993 Canadian Federal Election

year	PQ	NDP	L	PC	SC	R/CA
1979		26	114	136	6	
1980		32	147	103		
1984		30	40	211		
1988		43	83	169		
1993	54	9	177	2		52

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lecture 3

Dynamics of Social Balance

Investigate dynamical rules that promote evolution to a *balanced* state

Socially Balanced States

unfrustrated/balanced

frustrated/imbalanced

Social Balance a friend of my friend an enemy of my enemy a friend of my enemy an enemy of my friend } is my enemy. Static properties of signed graphs:

Balanced states on complete graph must either be

- *utopia*: only friendly links
- *bipolar*: two mutually antagonistic cliques

Cartwright & Harary (1956)

Two Natural Evolution Rules

Local Triad Dynamics:

reduce imbalance in one triad by single update

 $1 \rightarrow$

→ Balance transition as a function of p

Global Triad Dynamics: reduce global imbalance by single update

→ Outcome unknown

Local Triad Dynamics on Arbitrary Networks (social graces of the clueless)

- I. Pick a random imbalanced (frustrated) triad
- **2. Reverse a single link so that the triad becomes balanced** probability p: unfriendly \rightarrow friendly; probability I-p: friendly \rightarrow unfriendly

Fundamental parameter p:

p=1/3: flip a random link in the triad equiprobably

- p>1/3: predisposition toward tranquility
- p<1/3: predisposition toward hostility

The Evolving State

rate equation for the density of friendly links ρ :

Simulations for a Finite Society

p>1/2: inversion of the rate equation $u \sim e^{-3(2p-1)t} \approx N^{-2} \rightarrow T_N \sim \frac{\ln N}{2p-1}$ u=1-p, the unfriendly link density p = 1/2

naive rate equation estimate:

$$u \equiv 1 - \rho \propto t^{-1/2} \approx N^{-2} \longrightarrow T_N \sim N^4$$

incorporating fluctuations as balance is approached:

$$U = Lu + \sqrt{L} \eta$$

$$\sim \frac{L}{\sqrt{t}} + \sqrt{L} t^{1/4}$$

equating the 2 terms in U: $T_N \sim L^{2/3} \sim N^{4/3}$

Possible Application I: Long Beach Street Gangs

gang relations

Possible Application II: A Historical Lesson

3 Emperor's League 1872-81

Triple Alliance 1882

German-Russian Lapse 1890

French-Russian Alliance 1891-94

Entente Cordiale 1904

British-Russian Alliance 1907

Axelrod Model

Axelrod (1997)

Me:

ecrea	tion
skiing	
hiking	

fishing hunting running politics leftist rightist anarchist apathetic fascist

abode

suburb house city apartment homeless pied-à-terre city house

Axelrod Model

Axelrod (1997)

Me:

cuisine
meat
vegetarian
vegan
fast weekly
dietina

recreation

skiing hiking fishing hunting running **politics** *leftist rightist anarchist apathetic fascist*

abode

suburb house city apartment homeless pied-à-terre city house

Axelrod Model

Axelrod (1997)

Me:

cuisine vegetarian

recreation

skiing hiking fishing hunting running

politics leftist rightist anarchist apathetic fascist

abode

suburb house city apartment homeless pied-à-terre city house

Axelrod's Simulation

F=5, q=10, 10x10 lattice

Axelrod ModelCastellano, Marsili & Vespignani (2000)simulations on 150 x 150 square lattice

Axelrod Model with F=2 on 4-regular graph

 $P_m \equiv$ fraction of links with *m* common features m = 0, 2 inactive; m = 1 active

Master Equations for Bond Densities

$$\dot{P}_0 = \frac{z-1}{z} P_1 \left[-\lambda P_0 + \frac{1}{2} P_1 \right]$$

$$\dot{P}_1 = -\frac{P_1}{z} + \frac{z-1}{z}P_1\Big[\lambda P_0 - \frac{1}{2}(1+\lambda)P_1 + P_2\Big]$$

direct processes
$$\dot{P}_2 = \frac{P_1}{z} + \frac{z-1}{z}P_1\left[\frac{1}{2}\lambda P_1 - P_2\right]$$
$$\Delta N_1 = -\frac{1}{2}P_1 \qquad \rightarrow \frac{\Delta P_1}{\Delta t} = -\frac{\frac{1}{2}P_1/L}{1/N} = -\frac{P_1}{z}$$



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$$\dot{P}_0 = \frac{z-1}{z} P_1 \Big[-\lambda P_0 + \frac{1}{2} P_1 \Big] \qquad \begin{aligned} d\tau &\equiv \frac{z-1}{z} P_1 dt \\ x &\equiv P_0 \\ y &\equiv P_1 \\ P_2 &= 1 - P_0 - P_1 \end{aligned}$$

$$\dot{P}_1 = -\frac{P_1}{z} + \frac{z-1}{z} P_1 \left[\lambda P_0 - \frac{1}{2} (1+\lambda) P_1 + P_2 \right]$$

$$\dot{P}_2 = \frac{P_1}{z} + \frac{z-1}{z} P_1 \left[\frac{1}{2}\lambda P_1 - P_2\right]$$

$$x' = -\lambda x + \frac{1}{2}y \qquad d\tau \equiv \frac{z-1}{z}P_1 dt$$
$$y' = \left(1 - \frac{1}{\eta}\right) + \left(\lambda - 1\right)x - \left(\frac{3+\lambda}{2}\right)y \qquad x \equiv P_0$$
$$y \equiv P_1$$
$$P_2 = 1 - P_0 - P_1$$









Axelrod Model with F=2

transition between steady state $(q < q_c) \&$ fragmented static state $(q > q_c)$

q<q_c: very slow approach to steady state with time scale $\simeq (q_c - q)^{-1/2}$

long transient in which $P_1 \simeq (q_c - q)$ before steady state is reached

Some Closing Thoughts

Voter Model well characterized, but:

consensus route incompletely understood on complex graphs
generalizations, role of heterogeneity, role of internal beliefs,
data-driven models

Models of Diversity & Discord

bifurcation sequence in bounded compromise
role of competing social interactions mostly unknown
mathematical understanding of Axelrod model lacking
data-driven models

Notes: physics.bu.edu/~redner: click the "slides from selected talks" link